Operating System Design

Processes Scheduling Review IPC: Pipes

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Processes

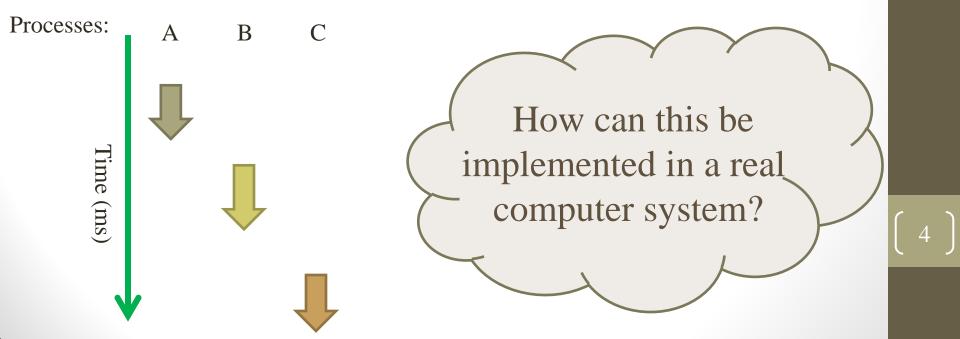
- What is a process?
 - Informally: a program in execution
- Examples of processes in a computer system
 - The Kernel and all its related processes
 - Web browser
 - Word editor
 - JVM
 - Python IDE
 - •
- How can you see the list of processes on your machine?
 - top, htop
 - ps -el

You want to design the OS to allow for multi processes running at the same time...

Assume there is one CPU!

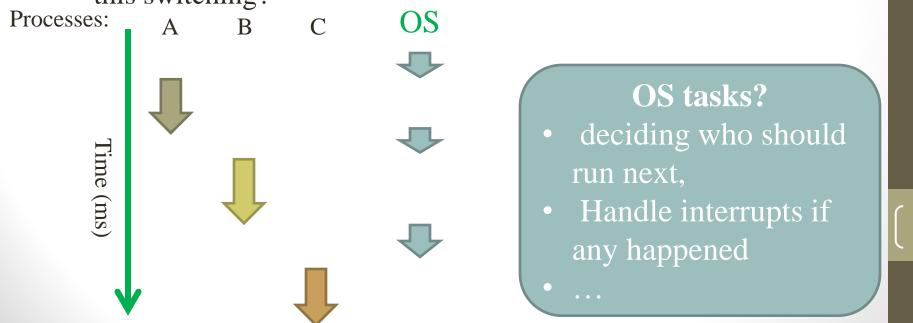
Specs of the multi-process Computer System with one CPU

- We want processes to run concurrently, so (i) they can interact with each other, and (ii) maximize CPU utilization
 - Fact: at each time only one process can run on each processor
 - Remedy: So, we should switch processes fast enough so they feel like they are all running simultaneously (illusion)



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- Can the OS kernel as the main process in the system perform this switching?



Specs of the multi-process Computer System with one CPU • We want processes to run concurrently, so (i) they can interact with each other, and (ii) maximize • Fact: at *p* or Rem like What does the OS need to know about the Processes Processes to be able to do this Switching? no should Time (ms IIII IIUAI

6

Processes Components

- What are the main components of a process?
 - Text section
 - The code
 - Stack
 - Local variables
 - Function parameters
 - ...
 - Heap
 - Dynamically allocated memory
 - Data Section
 - Global variables
 - What else?

Processes Components

- Assume processes A is running in a system
 - The CPU decides to switch from process A to another process
 - What information will the CPU need to resume process A later?
 - Program Counter
 - Value of registers

Text section

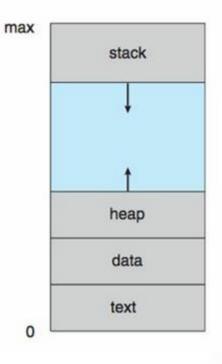
• SO, a process is associated with the following components

Text section	Process A
 Data section 	lw \$t0, offset(\$s0)
• Heap	lw \$t1, offset(\$s1)
• Stack	add \$d, \$t0, \$t1
Program Counter	•
 Value of Registers 	•



Processes Components

- A process is associated with the following components
 - Text section
 - Data section
 - Heap
 - Stack
 - Program Counter
 - Value of Registers
- The process in memory looks like this



What other information is needed?

- If you want to design a scheduler to divide your time resource between a bunch of different processes, what info would you need in order to schedule effectively and fairly
 - Process state running, waiting, etc
 - Program counter location of instruction to next execute
 - CPU registers contents of all process-centric registers
 - CPU scheduling information- priorities, scheduling queue pointers
 - Memory-management information memory allocated to the process
 - Accounting information CPU used, clock time elapsed since start, time limits
 - I/O status information I/O devices allocated to process, list of open files

Where to keep that information?

• There is a data type called Process Control Block (PCB) that contains all this information about each process

process state

process number

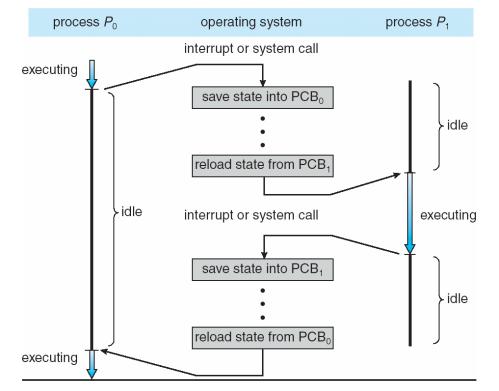
program counter

registers

memory limits

list of open files

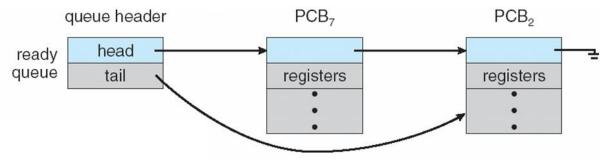
CPU Switch between Processes



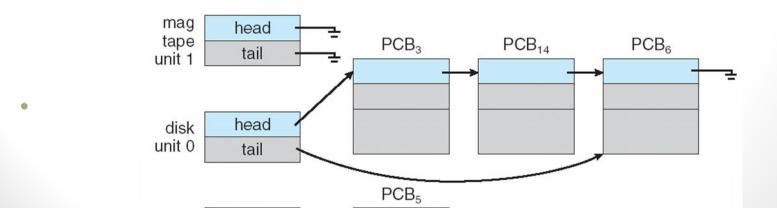
- Context Switch: When CPU switches to another process, the system must save the state of the old process and load the saved state for the new process via a context switch
- This time is pure overhead!

Scheduler

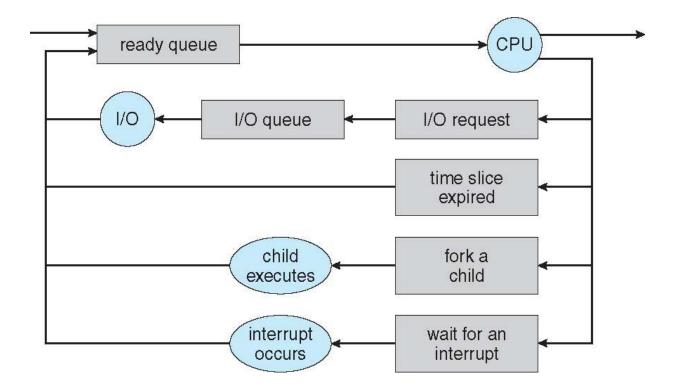
• A list of all processes PCBs is available to OS scheduler



- Ready queue: a list of all processes which are ready and waiting to execute
- Device queue: a list of all processes waiting for an I/O operation on a device, e.g., Disk queue, terminal queue



Scheduler



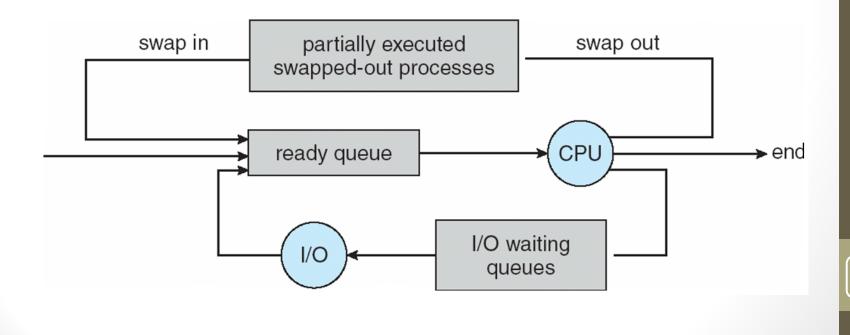


Scheduler

- Short-term scheduler (or CPU scheduler) selects which process should be executed next and allocates CPU
 - Sometimes the only scheduler in a system
 - Short-term scheduler is invoked frequently (milliseconds) ⇒ (must be fast)
- Long-term scheduler (or job scheduler) selects which processes should be brought into the ready queue
 - Long-term scheduler is invoked infrequently (seconds, minutes) ⇒ (may be slow)
 - The long-term scheduler controls the **degree of multiprogramming**
- Processes can be described as either:
 - I/O-bound process spends more time doing I/O than computations, many short CPU bursts
 - CPU-bound process spends more time doing computations; few very long CPU bursts
- Long-term scheduler strives for good *process mix*

Medium-Term Scheduler

- Medium-term scheduler can be added if degree of multiple programming needs to decrease
 - Remove process from memory, store on disk, bring back in from disk to continue execution: swapping



IPC: Pipes

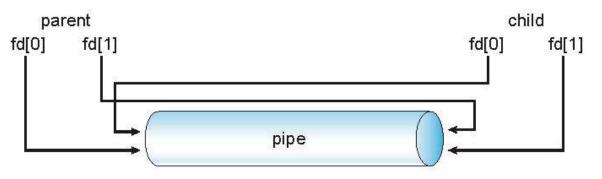
[17]

Pipes

- Acts as a channel allowing two processes to communicate
- Issues:
 - Is communication unidirectional or bidirectional?
 - In the case of two-way communication, is it half or full-duplex?
 - Must there exist a relationship (i.e., *parent-child*) between the communicating processes?
 - Can the pipes be used over a network?
- Ordinary pipes cannot be accessed from outside the process that created it. Typically, a parent process creates a pipe and uses it to communicate with a child process that it created.
- Named pipes can be accessed without a parent-child relationship.

Ordinary Pipes

- Ordinary Pipes allow communication in standard producer-consumer style
- Producer writes to one end (the **write-end** of the pipe)
- Consumer reads from the other end (the **read-end** of the pipe)
- Ordinary pipes are therefore unidirectional
- Require parent-child relationship between communicating processes

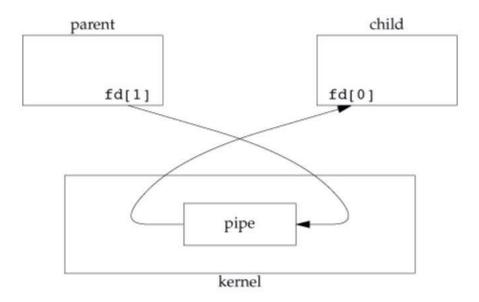


• Windows calls these **anonymous pipes**

Pipes: creation and setup

#include <unistd.h>

int pipe(int fd[2]);



- \succ The data in the pipe flows through the kernel.
- Normally, the process that calls pipe then calls fork, creating an IPC channel from the parent to the child, or vice versa.



Pipes: creation and setup

```
#include "apue.h"
int
main(void)
{
    int
           n;
    int fd[2];
   pid t pid;
    char line[MAXLINE];
    if (pipe(fd) < 0)
        err sys("pipe error");
    if ((pid = fork()) < 0) {
        err sys("fork error");
    } else if (pid > 0) {
                          /* parent */
        close(fd[0]);
        write(fd[1], "hello world\n", 12);
                                /* child */
    } else {
        close(fd[1]);
       n = read(fd[0], line, MAXLINE);
       write(STDOUT FILENO, line, n);
    }
    exit(0);
}
```

21

Named Pipes

- Named Pipes are more powerful than ordinary pipes
- Communication is bidirectional
- No parent-child relationship is necessary between the communicating processes
- Several processes can use the named pipe for communication
- Provided on both UNIX and Windows systems

Activity!

23