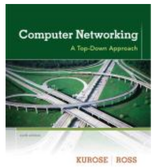
Chapter 4
Network Layer



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Thanks and enjoy! JFK/KWR

Computer Networking: A Top Down Approach
6th edition
Jim Kurose, Keith Ross
Addison-Wesley
March 2012

The course notes are adapted for Bucknell's CSCI 363
Xiannong Meng
Spring 2016

Chapter 4: outline

Distance vector algorithm

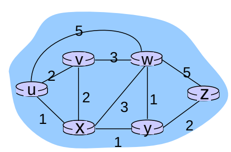
Bellman-Ford equation (dynamic programming)

let
$d_x(y)$:= cost of least-cost path from x to y
then

$$d_x(y) = \min_v \{c(x,v) + d_v(y)\}$$

cost from neighbor v to destination y
cost to neighbor v
min taken over all neighbors v of x

Bellman-Ford example



Assume we have computed,
$d_v(z) = 5$, $d_x(z) = 3$, $d_w(z) = 3$

B-F equation says:

$$d_u(z) = \min \{ c(u,v) + d_v(z), c(u,x) + d_x(z), c(u,w) + d_w(z) \} = \min \{2 + 5, 1 + 3, 5 + 3\} = 4$$

node achieving minimum (in our case, *x*) is next hop in shortest path, used in forwarding table

Distance vector algorithm

- $D_x(y)$ = estimate of least cost from x to y
  - x maintains distance vector $\mathbf{D}_x = [D_x(y): y \in N]$
- node x:
  - knows cost to each neighbor v: $c(x,v)$
  - maintains its neighbors' distance vectors. For each neighbor v, x maintains
    $\mathbf{D}_v = [D_v(y): y \in N]$

Distance vector algorithm

key idea:

- from time-to-time, each node sends its own distance vector estimate to neighbors
- when x receives new DV estimate from neighbor, it updates its own DV using B-F equation:

$$D_x(y) \leftarrow \min_v \{c(x,v) + D_v(y)\} \quad \text{for each node } y \in N$$

- under minor, natural conditions, the estimate $D_x(y)$ *converge to the actual least cost* $d_x(y)$

Distance vector algorithm

iterative, asynchronous: each local iteration caused by:

- local link cost change
- DV update message from neighbor

distributed:

- each node notifies neighbors *only* when its DV changes
  - neighbors then notify their neighbors if necessary

each node:

wait for (change in local link cost or msg from neighbor)

recompute estimates

if DV to any dest has changed, *notify* neighbors

$D_x(y) = \min\{c(x,y) + D_y(y),\ c(x,z) + D_z(y)\}$
$= \min\{2+0\ ,\ 7+1\} = 2$

$D_x(z) = \min\{c(x,y) + D_y(z),\ c(x,z) + D_z(z)\}$
$= \min\{2+1\ ,\ 7+0\} = 3$

node x table

from \ cost to	x	y	z
x	0	2	7
y	∞	∞	∞
z	∞	∞	∞

from \ cost to	x	y	z
x	0	2	3
y	2	0	1
z	7	1	0

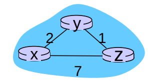
node y table

from \ cost to	x	y	z
x	∞	∞	∞
y	2	0	1
z	∞	∞	∞

node z table

from \ cost to	x	y	z
x	∞	∞	∞
y	∞	∞	∞
z	7	1	0

time



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node y table

from \ cost to	x	y	z
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z	∞	∞	∞

from \ cost to	x	y	z
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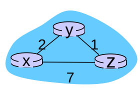
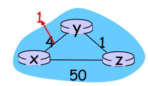


Distance vector: link cost changes

link cost changes:

- node detects local link cost change
- updates routing info, recalculates distance vector
- if DV changes, notify neighbors



"good news travels fast"

t_0 : *y* detects link-cost change, updates its DV, informs its neighbors.

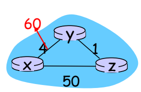
t_1 : *z* receives update from *y*, updates its table, computes new least cost to *x* , sends its neighbors its DV.

t_2 : *y* receives *z*'s update, updates its distance table. *y*'s least costs do *not* change, so *y* does *not* send a message to *z*.

Distance vector: link cost changes

link cost changes:

- node detects local link cost change
- *bad news travels slow* - "count to infinity" problem, e.g., c(x,y) is changed from 4 to 60
- Initially, $D_y(x) = 4$, $D_z(x) = 5$, so next update leads to $D_y(x) = 6$, $D_z(x) = 7$, next, $D_y(x) = 8$, $D_z(x) = 9$, …



the "count-to-infinity problem"

poisoned reverse:

- If Z routes through Y to get to X :
  - Z tells Y its (Z's) distance to X is infinite (so Y won't route to X via Z)
- will this completely solve count to infinity problem?

Other means to tackle count-to-infinity

- Split-horizon: if a node *X* learns the route to *Y* through *Z*, the X should not be part of the advertising to node *Z* to reach *Y*.
- Hold-down timer: a router starts a hold-down-timer when new routing information is available. It doesn't update its own routing information until the timer expires.

https://www.techopedia.com/definition/14850/split-horizon
https://www.techopedia.com/definition/25073/hold-down-timer

Comparison of LS and DV algorithms

message complexity
- ***LS:*** with n nodes, E links, O(nE) msgs sent
- ***DV:*** exchange between neighbors only
  - convergence time varies

speed of convergence
- ***LS:*** $O(n^2)$ algorithm requires O(nE) msgs
  - may have oscillations
- ***DV:*** convergence time varies
  - may be routing loops
  - count-to-infinity problem

robustness: what happens if router malfunctions?

LS:
- node can advertise incorrect *link* cost
- each node computes only its *own* table

DV:
- DV node can advertise incorrect *path* cost
- each node's table used by others
  - error propagate thru network

Chapter 4: outline

Hierarchical routing

our routing study thus far - idealization
- all routers identical
- network "flat"

… *not* true in practice

scale: with 600 million destinations:
- can't store all dest's in routing tables!
- routing table exchange would swamp links!

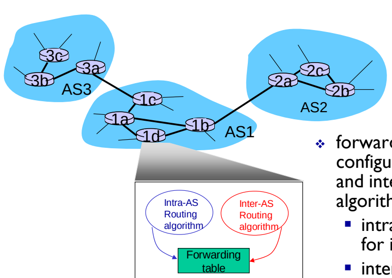
administrative autonomy
- internet = network of networks
- each network admin may want to control routing in its own network

Hierarchical routing

- aggregate routers into regions, "autonomous systems" (AS)
- routers in same AS run same routing protocol
  - "intra-AS" routing protocol
  - routers in different AS can run different intra-AS routing protocol

gateway router:
- at "edge" of its own AS
- has link to router in another AS

Interconnected ASes



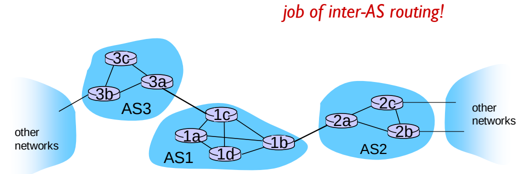
- forwarding table configured by both intra- and inter-AS routing algorithm
  - intra-AS sets entries for internal dests
  - inter-AS & intra-AS sets entries for external dests

Inter-AS tasks

- suppose router in AS1 receives datagram destined outside of AS1:
  - router should forward packet to gateway router, but which one?

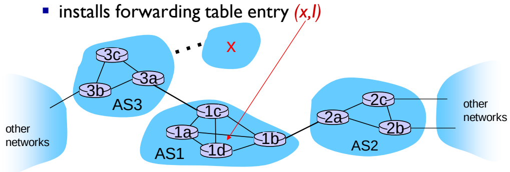
AS1 must:
1. learn which dests are reachable through AS2, which through AS3
2. propagate this reachability info to all routers in AS1

job of inter-AS routing!



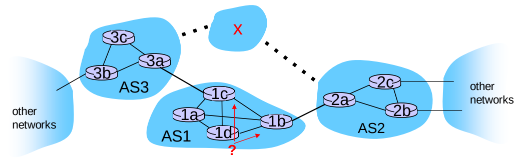
Example: setting forwarding table in router 1d

- suppose AS1 learns (via inter-AS protocol) that subnet *x* reachable via AS3 (gateway 1c), but not via AS2
  - inter-AS protocol propagates reachability info to all internal routers
- router 1d, which has three out-going links (1 for c, 2 for a,3 for b), determines from intra-AS routing info that its interface *I* is on the least cost path to 1c
  - installs forwarding table entry *(x,I)*



Example: choosing among multiple ASes

- now suppose AS1 learns from inter-AS protocol that subnet *x* is reachable from AS3 *and* from AS2.
- it is the job of inter-AS routing protocol to determine which gateway it should forward packets towards for dest x



Example: choosing among multiple ASes

- in the presence of multiple ASes to reach a destination, to configure forwarding table, router 1d must determine towards which gateway it should forward packets for dest x
- *hot potato routing: send* packet towards closest of two routers. (closest → smallest cost)