#### Hash Maps Introduction

Revised based on textbook author's notes.

#### Introduction

- When discussing search we saw:
  - linear search O(n)
  - binary search O( log n )
- Can we improve the search operation to achieve better than O( log n ) time?

#### **Comparison-Based Searches**

- To locate an item, the target search key has to be compared against the other keys in the collection.
  - O(log n) is the best that can be achieved.
  - We must use a different technique if we want to improve the search time.

### Hashing

- The process of mapping a search key to a limited range of array indices.
  - The goal is to provide direct access to the keys.
  - **hash table** the array containing the keys.
  - **hash function** maps a key to an array index.

# Hashing Example

- Suppose we have a list of popular fruits, we want to find if a particular type of fruit is in our inventory.
- Apple, Banana, Grape, Orange, Pear, Pineapple, Strawberry.
- We could use an array of 26 elements, each is index by the first letter of the fruit name, assuming no repetition. We can simply check for fruit[name[0]]!

# Hashing Example

• Suppose we have the following set of keys

765, 431, 96, 142, 579, 226, 903, 388

a hash table, T, with M = 13 elements.

- We can define a simple hash function h() h(key) = key % M
- h(765) -> 11, h(431) -> 2, ...

# Adding Keys

- To add a key to the hash table:
  - Apply the hash function to determine the array index in which the key should be stored.

• Store the key in the given slot.



#### Collisions

• What happens when we attempt to add key 226?



### Resolving collisions

- There are in general two approaches to resolve collisions,
  - Closed hashing: find a spot within the hash table to store the new element
  - Open hashing: create a structure, e.g., a list, or a tree, in the hashed spot to store the elements that have the same hashing key
- We first concentrate on closed hashing.

### Closed hashing: probing

- If two keys map to the same table entry, we must resolve the collision to find another available slot.
  - **linear probe** simplest approach which examines the table entries in sequential order.



#### Probing

• Consider adding key 903 to our hash table.



# Probing

- If the end of the array is reached during the probe, it wraps around to the first entry and continues.
  - Consider adding key 388 to our hash 388: '65226 579 903

### Searching

- Searching a hash table for a specific key is very similar to the add operation.
  - Target key is mapped to an initial slot.
  - See if the slot contains the target.
  - Otherwise, apply the same probe used to add keys to locate the target.



### Searching

- What if the key is not in the hash table? ►X 226 579 903 '65
- The probe continues until either:
  - a null reference is reached, or
  - all slots have been examined.

# Deleting Keys

- Deleting a key from a hash table is a bit more complicated than adding keys.
  - We can search for the key to be deleted.
  - But we cannot simply remove it by setting the entry to None.

#### **Incorrect** Deletion

• Suppose we simply remove key 226 from slot 6.



• What happens if we search for key 903?



#### **Correct Deletion**

• We use a special flag to indicate the entry is now empty, but was previously occupied.



• When searching a hash table, the probe must continue past the slot(s) with the special flag.



# Clustering

- The grouping of keys in a common area.
  - As more keys are added to the hash table, more collisions are likely to occur.
  - Clusters begin to form due to the probing required to find an empty slot.
  - As a cluster grows larger, more collisions will occur.
- **primary clustering** clustering around the original hash position.

# Probe Sequence

- The order in which the hash entries are visited during a probe.
  - The linear probe steps through the entries in sequential order.
  - The next array slot can be represented as

```
slot = (home + i) % M
```

- where
  - i is the i<sup>th</sup> probe.
  - home is the **home position**

#### Modified Linear Probe

• We can improve the linear probe by changing the step size to some fixed constant.

slot = (home + i \* c) % M

- Suppose we set c = 3 to build the hash table.  $h(765) \Rightarrow 11$  $h(431) \Rightarrow 2$  $h(579) \Rightarrow 7$  $h(226) \Rightarrow 5 \Rightarrow 8$ 
  - h(96) => 5h(903) => 6h(142) => 12h(388) => 11 => 1



#### Quadratic Probing

• A better approach for reducing primary clustering.

slot = (home + i\*\*2) % M

- Increases the distance between each probe in the sequence.
- Example:



#### Computations from last slide

• Quadratic probing

h(765)	=>	11	h(579)	=>	7								
h(431)	=>	2	h(226)	=>	5	=>	6						
h(96)	=>	5	h(903)	=>	6	=>	7	=>	10				
h(142)	=>	12	h(388)	=>	11	=>	12	=>	2	=>	7	=>	1



### Quadratic Probing

- Reduces the number of collisions.
- Introduces the problem of **secondary clustering**.
  - When two keys map to the same entry and have the same probe sequence.
- Example: add key 648
  - hashes to entry 11
  - follows the same sequence as key 388



### Double Hashing

• When a collision occurs, a second hash function is used to build a probe sequence.

slot = (home + i \* hp(key)) % M

- Step size remains a constant throughout the probe.
- Multiple keys that have the same home position, will have different probe sequences.

### Double Hashing

• A simple choice for the second hash function.

hp(key) = 1 + key % P

• Example: let P = 8





#### Computations from last slide

#### • Double hashing

- slot = (home + i \* hp(key)) % M, e.g., M==13
- hp(key) = 1 + key % P, e.g., P == 8

h(765)	=>	11	h(579)	=>	7		
h(431)	=>	2	h(226)	=>	5	=> 8	}
h(96)	=>	5	h(903)	=>	6		
h(142)	=>	12	h(388)	=>	11	=> 3	3

h(226) => 5, double hashing [(5+1\*(1+226))%P] % M => 8 h(388) => 11, double hasing [(11+1\*(1+388)%P] % M => 3

