

## IN-CLASS WORK: MOLECULAR DYNAMICS SIMULATION (DRIVEN DAMPED PENDULUM)

You find the solutions to the previous classes on molecular simulations for example in

`~kvollmay/share.dir/inclass2023.dir/md3.py`

At the beginning of class I will introduce the equations of motion for the driven damped pendulum.

### 6. Driven Damped Pendulum Intro & Trajectory

6a. We just derived the essential equation for the simulation of the driven, damped pendulum to be

$$\frac{d^2\theta}{dt^2} = \tilde{A} \cos(\tilde{\omega}_D t) - \sin(\theta) - \tilde{\gamma} \frac{d\theta}{dt} \quad (4)$$

where we replaced  $\tilde{t}$  by  $t$  simply for the convenience of notation. In the computer simulation we solve this equation numerically, i.e. our goal is to determine  $\theta(t)$  and  $\dot{\theta}(t)$ .

Using the Euler method as written on the white board, program this driven damped pendulum. Use

$$\theta_0 = -2.5 \quad \omega_0 = 0.0 \quad \tilde{A} = 0.95 \quad \tilde{\omega}_D = 2.0/3.0 \quad \tilde{\gamma} = 0.5 \quad \Delta t = 0.01 \quad n_{\max} = 10000$$

Print only every 10th MD-step  $t, \theta(t), \omega(t)$ . (In the following I will call this `nprint=10`.) Look at  $\theta(t)$  and  $\omega(t)$ . If your data are in the file `out6sim.dat` you can do this with `xmgrace -block out6sim.dat -bxy 1:2 -bxy 1:3 -legend load`

6b What is the energy of the driven damped pendulum? Since we chose as time unit  $1/\omega_{\text{SHO}}$  and as moment of inertia unit  $I$  our energy unit is  $I\omega_{\text{SHO}}^2$  and this means that in the program you want to determine  $\tilde{E} = \frac{E}{I\omega_{\text{SHO}}^2}$ . Please get me when you have your expression for  $\tilde{E}$ . Then add the determination of  $\tilde{E}$  to your program and print  $\tilde{E}(\tilde{t})$  and look at your results with `xmgrace`. Get me also when you have your result. We will discuss the interpretation of your result.

### 7. Period Doubling (if time)

Next we will vary  $\tilde{A}$  and will observe how  $\tilde{A}$  influences  $\theta(t)$  and  $\omega(t)$ . For this task and also for next class, we will use a special time step  $\Delta t$ . We will use

$$\Delta t = \frac{2\pi}{\tilde{\omega}_D N_{\text{dt}}}$$

Please ask when you get to this, I will briefly explain why we choose  $\Delta t$  this way. Use  $N_{\text{dt}} = 200$  and increase `nmax` to 100000.

7a. Look at  $\theta(t), \omega(t)$  and  $E(t)$  for  $\tilde{A} = 1.049$ .

**7b.** Look at  $\theta(t)$ ,  $\omega(t)$  and  $E(t)$  for  $\tilde{A} = 1.053$ .

**7c.** Look at  $\theta(t)$ ,  $\omega(t)$  and  $E(t)$  for  $\tilde{A} = 1.054$ .

**7d.** Look at  $\theta(t)$ ,  $\omega(t)$  and  $E(t)$  for  $\tilde{A} = 1.07$ .

**7e.** Get me when you got all results for 7a-7d. (Get them all on the screen, so that your class members can see them also.)