# BUCKNELL UNIVERSITY Computer Science

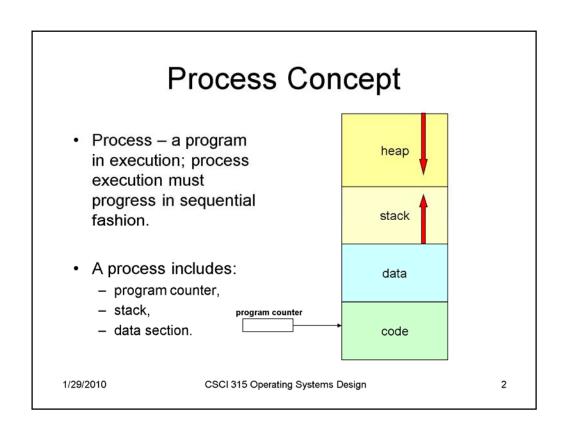
## **CSCI 315 Operating Systems Design**

#### **Processes**

<u>Notice:</u> The slides for this lecture have been largely based on those accompanying an earlier edition of the textbook *Operating Systems Concepts with Java*, by Silberschatz, Galvin, and Gagne. Many, if not all, the illustrations contained in this presentation come from this source.

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## Process Control Block (PCB)

## OS bookkeeping information associated with each process:

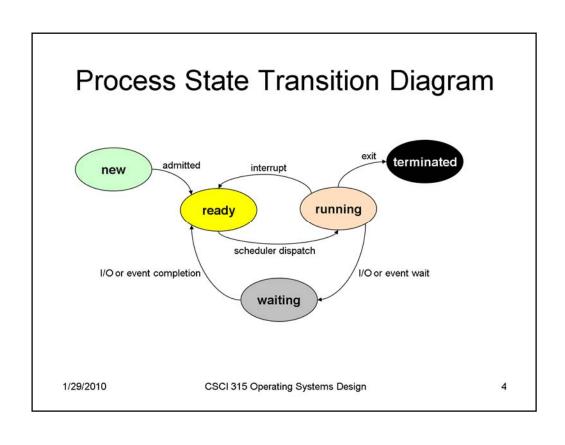
- · Process state,
- · Program counter,
- · CPU registers,
- · CPU scheduling information,
- · Memory-management information,
- · Accounting information,
- I/O status information,

:

process id
process state
program counter
registers
memory limits
list of open files
:

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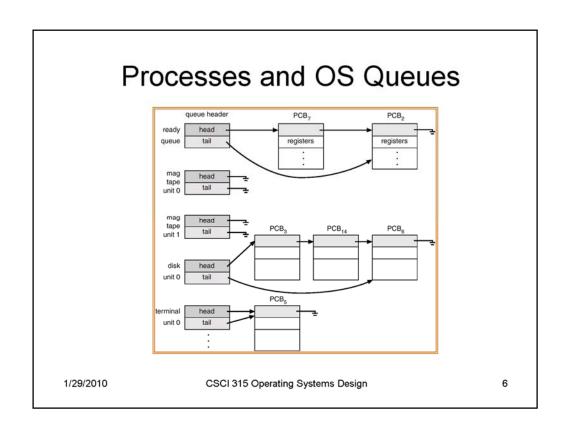
## **Process Scheduling Queues**

- Job queue set of all processes in the system.
- Ready queue set of all processes residing in main memory, ready and waiting to execute.
- Device queues set of processes waiting for an I/O device.

Processes migrate between the various queues.

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#### Schedulers

- Long-term scheduler (or job scheduler) selects which processes should be brought into the ready queue
- Short-term scheduler (or CPU scheduler)
   selects which process should be executed next and allocates CPU

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#### **Schedulers**

- Short-term scheduler is invoked very frequently (milliseconds) ⇒ (must be fast)
- Long-term scheduler is invoked very infrequently (seconds, minutes) ⇒ (may be slow; controls the degree of multiprogramming)
- Processes can be described as either:
  - I/O-bound process spends more time doing I/O than computations, many short CPU bursts
  - CPU-bound process spends more time doing computations; few very long CPU bursts

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#### **Context Switch**

- When CPU switches to another process, the system must save the state of the old process and load the saved state for the new process.
- Context-switch time is overhead; the system does no useful work while switching.
- · Time dependent on hardware support.

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#### **Process Creation**

- Parent process create children processes, which, in turn can create other processes, forming a tree of processes.
- Resource sharing:
  - Parent and children share all resources,
  - Children share subset of parent's resources,
  - Parent and child share no resources.
- · Execution:
  - Parent and children execute concurrently,
  - Parent may wait until children terminate.

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## **Process Creation (Cont.)**

- · Address space:
  - Child has duplicate of parent's address space, or
  - Child can have a program loaded onto it.
- · UNIX examples:
  - fork system call creates new process and returns with a pid (0 in child, > 0 in the parent),
  - exec system call can be used after a fork to replace the process' memory space with a new program.

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#### **Process Termination**

- Process executes last statement and asks the operating system to terminate it (exit)
  - Output data from child to parent (via wait)
  - Process' resources are deallocated by operating system
- Parent may terminate execution of children processes (abort) if:
  - Child has exceeded allocated resources,
  - Task assigned to child is no longer required,
  - If parent is exiting (some operating system do not allow child to continue if its parent terminates)
    - All children terminated cascading termination

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## **Cooperating Processes**

- An independent process cannot affect or be affected by the execution of another process.
- A cooperating process can affect or be affected by the execution of another process.
- · Advantages of process cooperation:
  - Information sharing,
  - Computation speed-up,
  - Modularity,
  - Convenience.

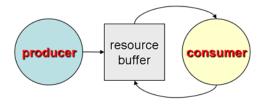
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## Producer-Consumer Problem

A paradigm for cooperating processes in which a *producer* process produces information that is consumed by a *consumer* process:

- unbounded-buffer places no practical limit on the size of the buffer.
- bounded-buffer assumes that there is a fixed buffer size.



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#### Bounded-Buffer

(shared-memory solution)

```
public interface Buffer
{
    // producers call this method
    public abstract void insert(Object
    item);

    // consumers call this method
    public abstract Object remove();
}
```

```
import java.util.*;
public class BoundedBuffer implements Buffer
{
    private static final int BUFFER SIZE = 5;
    private int count; // number of items in the buffer
    private int in; // points to the next free position
    private Object[] buffer;
    public BoundedBuffer() {
        // buffer is initially empty
        count = 0;
        out = 0;
        out = 0;
        buffer = new Object[BUFFER SIZE];
    }
    // producers calls this method
    public void insert(Object item) { // Slide 17 }
    // consumers calls this method
    public Object remove() { // Slide 18 }
}
```

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#### **Bounded-Buffer**

(shared-memory solution)

```
public void insert(Object item) {
   while (count == BUFFER SIZE); // do nothing -- no free buffers
   // add an item to the buffer
   ++count;
   buffer[in] = item;
   in = (in + 1) % BUFFER SIZE;
}
```

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#### **Bounded-Buffer**

(shared-memory solution)

```
public Object remove() {
    Object item;
    while (count == 0); // do nothing -- nothing to consume
    // remove an item from the buffer
    --count;
    item = buffer[out];
    out = (out + 1) % BUFFER SIZE;
    return item;
}
```

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## Interprocess Communication

(IPC)

- Mechanism for processes to communicate and to synchronize their actions
- Message system processes communicate with each other without resorting to shared variables
- IPC facility provides two operations:
  - send(message) message size fixed or variable
  - receive(message)
- If P and Q wish to communicate, they need to:
  - establish a communication link between them
  - exchange messages via send/receive
- Implementation of communication link
  - physical (e.g., shared memory, hardware bus)
  - logical (e.g., logical properties)

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## Implementation Questions

- · How are links established?
- Can a link be associated with more than two processes?
- How many links can there be between every pair of communicating processes?
- What is the capacity of a link?
- Is the size of a message that the link can accommodate fixed or variable?
- · Is a link unidirectional or bi-directional?

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## **Direct Communication**

- · Processes must name each other explicitly:
  - send (P, message) send a message to process P
  - receive(Q, message) receive a message from process Q
- · Properties of communication link
  - Links are established automatically
  - A link is associated with exactly one pair of communicating processes
  - Between each pair there exists exactly one link
  - The link may be unidirectional, but is usually bi-directional

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## **Indirect Communication**

- Messages are directed and received from mailboxes (also referred to as ports)
  - Each mailbox has a unique id
  - Processes can communicate only if they share a mailbox
- · Properties of communication link
  - Link established only if processes share a common mailbox
  - A link may be associated with many processes
  - Each pair of processes may share several communication links
  - Link may be unidirectional or bi-directional

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## **Indirect Communication**

- Operations:
  - create a new mailbox,
  - send and receive messages through mailbox,
  - destroy a mailbox.
- · Primitives are defined as:

**send**(*A, message*) – send a message to mailbox A,

**receive**(*A, message*) – receive a message from mailbox A.

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## **Indirect Communication**

- · Mailbox sharing
  - $-P_1$ ,  $P_2$ , and  $P_3$  share mailbox A
  - $-P_1$ , sends;  $P_2$  and  $P_3$  receive
  - Who gets the message?
- Solutions
  - Allow a link to be associated with at most two processes
  - Allow only one process at a time to execute a receive operation
  - Allow the system to select arbitrarily the receiver.
     Sender is notified who the receiver was.

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## Synchronization

- Message passing may be either blocking or nonblocking.
- Blocking is considered synchronous:
  - Blocking send has the sender block until the message is received.
  - Blocking receive has the receiver block until a message is available.
- Non-blocking is considered asynchronous
  - Non-blocking send has the sender send the message and continue.
  - Non-blocking receive has the receiver receive a valid message or null.

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## **Buffering**

Queue of messages attached to the link; implemented in one of three ways:

- Zero capacity 0 messages
   Sender must wait for receiver (rendezvous).
- 2. Bounded capacity finite length of *n* messages. Sender must wait if link full.
- Unbounded capacity infinite length. Sender never waits.

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